

Characterising State Spaces of Concurrent Systems

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Work started with Philippe Darondeau
and continued with Raymond Devillers

Open Problems in Concurrency Theory
Bertinoro, June 18, 2014

System analysis vs. system synthesis

- **Analysis**

Given: a system (program, algorithm, expression, Petri net)

Objective: deduce behavioural properties

State space **exploration** / **representation** / **explosion**

- **Synthesis**

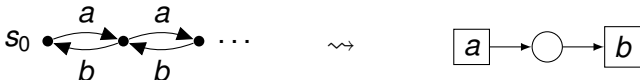
Given: a specification describing desired behaviour

Objective: derive a generating / implementing system

Correctness by design

Synthesis of Petri nets

- **Input** A labelled transition system (S, \rightarrow, T, s_0) with states S (initially s_0), labels T , arcs $\rightarrow \subseteq (S \times T \times S)$
- **Output** A marked Petri net with transitions T and isomorphic state space



Region theorems for an lts $TS = (\mathcal{S}, \rightarrow, T, s_0)$

- $(\mathbb{R}, \mathbb{B}, \mathbb{F}) \in (\mathcal{S} \rightarrow \mathbb{N}, T \rightarrow \mathbb{N}, T \rightarrow \mathbb{N})$ **region** of TS if
$$s \xrightarrow{t} s' \Rightarrow \mathbb{R}(s) \geq \mathbb{B}(t) \text{ and } \mathbb{R}(s') = \mathbb{R}(s) - \mathbb{B}(t) + \mathbb{F}(t)$$

A region 'behaves like a Petri net place' but is defined on TS

- TS satisfies **ESSP (event/state separation property)** if
$$\neg(s \xrightarrow{t}) \Rightarrow \exists \text{ region } (\mathbb{R}, \mathbb{B}, \mathbb{F}) \text{ with } \mathbb{R}(s) < \mathbb{B}(t)$$
- ... and **SSP (state separation property)** if
$$s \neq s' \Rightarrow \exists \text{ region } (\mathbb{R}, \mathbb{B}, \mathbb{F}) \text{ with } \mathbb{R}(s) \neq \mathbb{R}(s')$$

Theorems (for finite lts):

ESSP $\Rightarrow \exists$ a language-equivalent Petri net

ESSP \wedge SSP $\Rightarrow \exists$ a Petri net with isomorphic reachability graph

Ehrenfeucht, Rozenberg et al.

Upcoming book by Badouel, Bernardinello, Darondeau

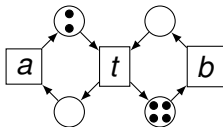
Checking the region properties, and open problems

- As far as I am aware, this theory has not yet been fully extended to infinite transition systems (but: Darondeau)
- For finite-state systems, the basic algorithm is polynomial
- **BUT** in the size of the lts!
- **AND** with exponents 7 or 8!
- The region theorems are pretty unwieldy
- Apparently, there is even no characterisation yet of the case that a finite straight lts (a word) satisfies ESSP
- If an lts is Petri net realisable there are usually many incomparable minimal solutions

Our approach Identify classes of lts for which structurally pleasant solutions can be shown to exist

A live and bounded marked graph

M_0
•



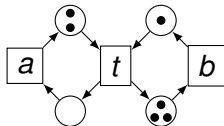
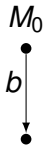
A **marked graph** Petri net

and its initial marking M_0

marked graph:

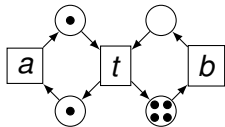
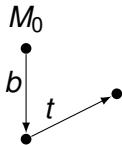
a Petri net with plain arcs and $|\bullet p| = 1 = |p\bullet|$ for all places p where $\bullet p$ = input transitions of p and $p\bullet$ = output transitions of p

A live and bounded marked graph



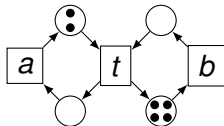
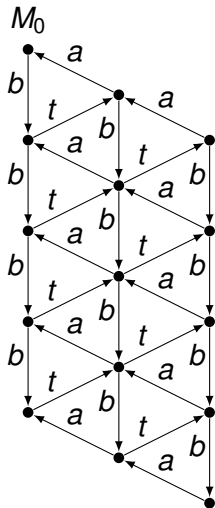
after executing b

A live and bounded marked graph



after executing bt

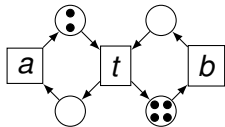
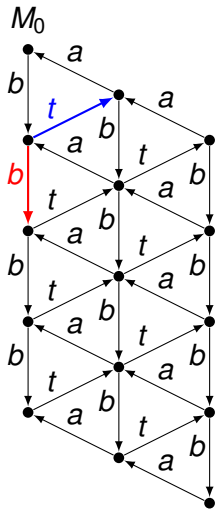
A live and bounded marked graph



A **marked graph** Petri net
and its **reachability graph**..

..which has several nice properties:

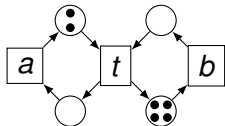
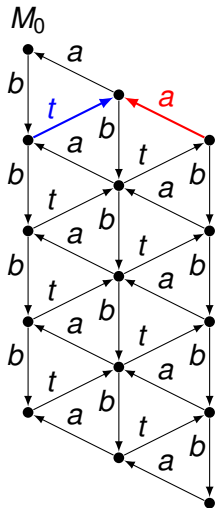
It is deterministic



Determinism If a state enables b and t , leading to different states, then $b \neq t$

.. true because the reachability graph comes from a Petri net

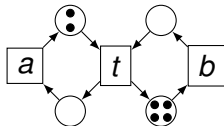
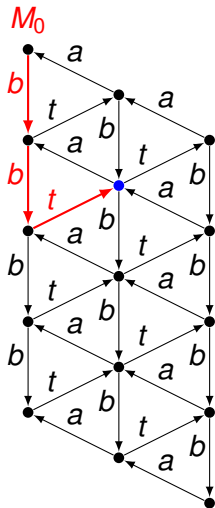
... and backward deterministic



Backward determinism If a and t lead to a state from different states, then $a \neq t$

.. true because the reachability graph comes from a Petri net

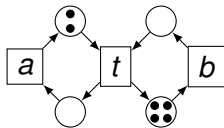
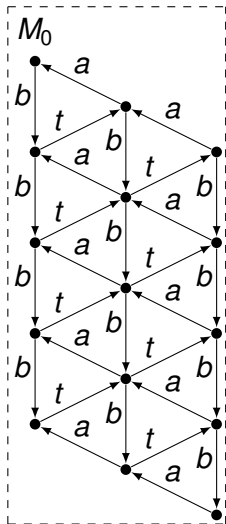
It is totally reachable



Total reachability Every state is reachable from the initial state M_0

.. true by the definition of reachability graph

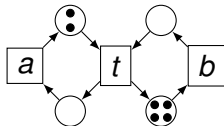
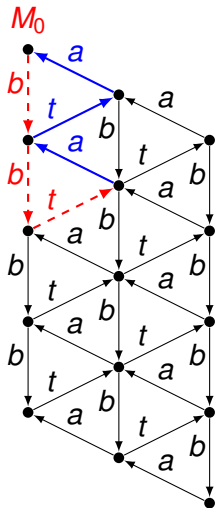
It is **finite**



Finiteness

..due to the boundedness of the net

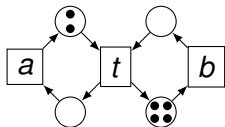
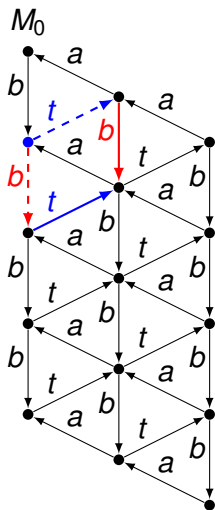
It is reversible



Reversibility The initial state is reachable from every reachable state

.. true (for marked graphs) by liveness and boundedness

It is persistent

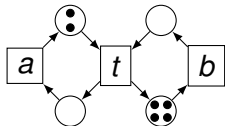
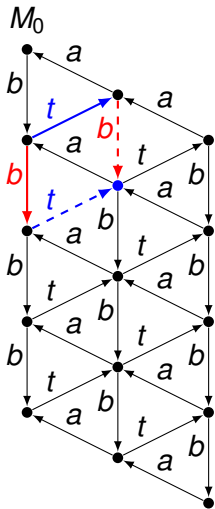


Persistency If a state enables b and t for $b \neq t$, then it also enables bt and tb

.. true by the marked graph property

also called *strong confluence*

It is backward persistent

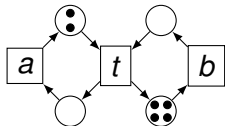
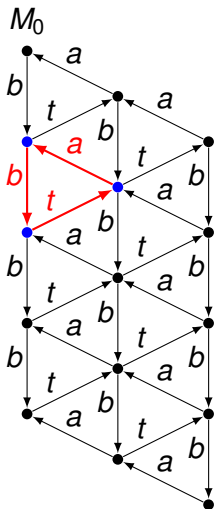


Backward persistency

If a state backward enables b and t for $b \neq t$, from two reachable states, then it also backward enables bt and tb

.. true by the marked graph property

It satisfies the **P1** property



The Parikh 1 property

In a small cycle, every firable transition occurs exactly once

.. true by the marked graph property

Note: $M_0 \xrightarrow{bbttaa} M_0$ is not small

small means:

nonempty and Parikh-minimal

State spaces of live and bounded marked graphs

Theorem The following are equivalent:

A TS is isomorphic to the reachability graph of a live and bounded marked graph

B TS is

- deterministic and backward deterministic
- totally reachable
- finite
- reversible
- persistent
- backward persistent
- and satisfies the P1 property of small cycles

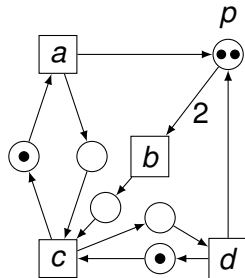
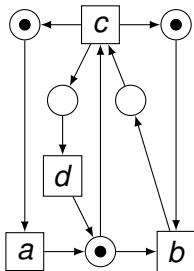
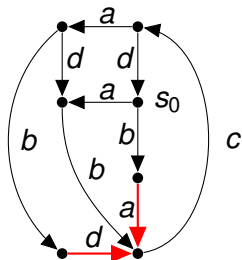
The proof of $\mathbf{A} \Rightarrow \mathbf{B}$ is in [Commoner, Genrich et al. \(1968—...\)](#)

The proof of $\mathbf{B} \Rightarrow \mathbf{A}$ is in LATA' 2014 (constructing regions)

Moreover: \exists a unique minimal marked graph realising TS

Necessity of backward persistency

The Its shown below satisfies all properties of **B** except backward persistency

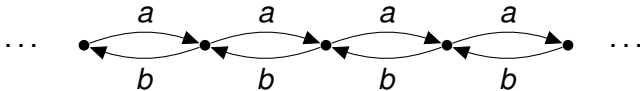


There is no marked graph solution

There are two different minimal non-marked graph solutions

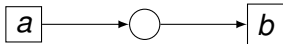
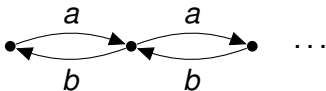
(Non-) solvable infinite Its

- The following infinite Its is **not** Petri net solvable:



Uniform 2-way infinite chains such as $\dots aaaa \dots$ or $\dots bbbb \dots$ cannot be part of a Petri net state space

- The following infinite Its is Petri net solvable:



Non-uniform 2-way infinite chains $\dots bbaa \dots$ are acceptable

State spaces of live, unbounded marked graphs

Theorem The following are equivalent:

- A** TS is isomorphic to the reachability graph of a live, unbounded marked graph
- B** TS is
 - deterministic and backward deterministic
 - totally reachable
 - infinite, but has no uniform 2-way infinite chains $\dots\alpha\alpha\alpha\alpha\dots$
 - reversible
 - persistent
 - backward persistent
 - and satisfies the P1 property of small cycles

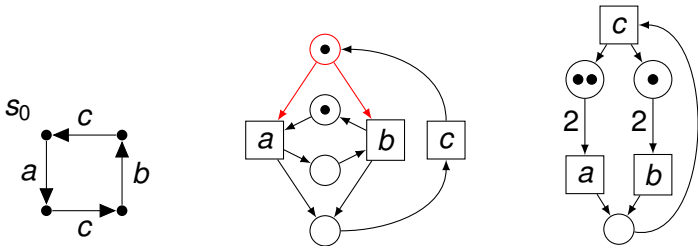
The proof of (**A** \Rightarrow **B**) is ‘common knowledge’

The proof of (**B** \Rightarrow **A**) is in a submitted paper (June 2014)

Moreover: \exists a unique minimal marked graph realising TS

Necessity of the P1 property

The Its shown below satisfies all properties of **B** except P1
By definition, it satisfies $P\Upsilon$ with $\Upsilon = (\#a, \#b, \#c) = (1, 1, 2)$



There is no marked graph solution

There are two different minimal non-marked graph solutions

The middle solution has a 'fake' (but non-redundant) choice

The r.h.s. solution is 'nicer' in the sense that it satisfies $|p^\bullet| \leq 1$

State spaces of reversible, bounded, ON Petri nets

ON (output-nonbranching): $|p^\bullet| \leq 1$ for all places p
(weakens the defining marked graph properties)

Theorem The following are equivalent:

A TS is isomorphic to the reachability graph of a reversible, bounded ON net

B TS is

- deterministic and totally reachable
- finite, reversible and persistent
- and satisfies the $P\Upsilon$ property of small cycles, with a constant Υ
- such that Υ enjoys $\gcd_{t \in T} \{\Upsilon(t)\} = 1$
- and for every $x \in T$ and maximal non- x -enabling state s the system

$$\forall r \in NUI(x): 0 < \sum_{1 \leq j \leq |T|} k_j \cdot (\Upsilon(t_j) \cdot (1 + \Delta_{r,s}(x)) - \Upsilon(x) \cdot \Delta_{r,s}(t_j))$$

has a nonnegative integer solution $k_1, \dots, k_{|T|}$

Υ : a Parikh vector (not necessarily 1, but the same for all small cycles)

$NUI(x)$: non- x -enabling states with a unique incoming arrow labelled x

$\Delta_{r,s}$: Parikh-distance between r and s (well-defined by some properties in **B**)

Proof: Using region theory again; see Petri Nets 2014 (Tunis, next week)

The inequalities in **B** only refer to proper (and 'small') subsets of states

Concluding remarks, and open problems

- The last result characterises finite, reversible, arbitrarily Petri net distributable (in the sense of Hopkins, Badouel et al.) Its
- Some Its are distributable but not arbitrarily so, and existing results would need to be extended
- Results tend to come with fast, dedicated synthesis algorithms
- ... whose complexity can not necessarily be analysed easily because of interdependencies of the sizes of special Its subsets
- Bounded non-labelled Petri nets also seem to give rise to a hierarchy inside regular languages that has, to my knowledge, not yet been deeply studied

In Petri net theory, several key (decidability) problems are still open

My favourite: the existence of a home state

Another favourite: language-equivalence under restrictions

The Nielsen, Thiagarajan conjecture still seems to be unsolved, too ...

Their conjecture has a flavour similar to the characterisation results mentioned in this talk, except that Its are replaced by event structures and a different class of Petri nets is concerned